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Real rep:  $M_T(f) = S M_T(f) S^{-1}$  if  $f$   $(*)$

①

$$\overline{T(f) \cdot v_i} = \overline{[M_T(f)]_{ji} v_j} = \overline{M_{\bar{T}}^*(f)_{ji} v_j}$$

$$\equiv \overline{T(f) v_i} = \overline{M_T(f)_{ji} v_j}$$

$$\Rightarrow M_T(f) = M_{\bar{T}}^*(f) \text{ , or } M_{\bar{T}}^*(f) = M_T(f)$$

$$\stackrel{(*)}{\Rightarrow} M_{\bar{T}}^*(f) = S M_T(f) S^{-1}$$

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$$(ii) (\tilde{T}(f_1) \cdot \phi)(v) = T_w(f_1) \cdot \phi(T_v(f_1^{-1})v)$$

$$\begin{aligned}
 [\tilde{T}(f_1)(\tilde{T}(f_2) \cdot \phi)](v) &= T_w(f_1) \cdot (\tilde{T}(f_2) \phi)(T_v(f_2^{-1})v) \\
 &= T_w(f_1) T_w(f_2) \phi(T_v(f_2^{-1}) T_v(f_1^{-1})v) \\
 &= T_w(f_1 f_2) \phi(T_v(f_1 f_2^{-1})v) \\
 &= [\tilde{T}(f_1 f_2) \phi](v), \text{ and}
 \end{aligned}$$

$$(\tilde{T}(e) \cdot \phi)(v) = T_w(e) \cdot \phi(T_v(e)v) = \phi(v)$$

(2)  $V^* := \text{Hom}(V, K) \cong V^* \otimes K$   $T_w$  acts trivially on  $K$ .

Rep. in (i) becomes

$$(\tilde{T}(f) v_i^*)(v_j) = v_i^* (T(f)^{-1} \cdot v_j)$$

which is exactly the dual rep we discussed in the lecture.

(2)

(3)  $V$  with basis  $\{v_i\}$ ,  $W$  with basis  $\{w_a\}$

$$\text{Hom}(V, W) \cong \text{Mat}_{m \times n}(\mathbb{C})$$

$$(\tilde{T}(f) \cdot \phi)(v) = T_w(f) \cdot \phi(T_v(f^{-1})v)$$

take  $\phi = e_{ai}$ ,  $e_{ai}(v_j) = w_a \delta_{ij}$

$$T_v j = \sum a_{ij} v_i$$

$$\begin{aligned} \# v_j : & [\tilde{T}(f) e_{ai}] (v_j) = T_w(f) \left\{ e_{ai} \left( \sum_k [M(f)]^k J_{kj} v_k \right) \right\} \\ &= T_w(f) \cdot \left( \sum_k [M(f)]^k J_{kj} e_{ai}(v_k) \right) \\ &= T_w(f) \left( \sum_k [M(f)]^k J_{kj} w_a \delta_{ik} \right) \\ &= T_w(f) \cdot [M(f)]^i J_{ij} w_a \\ &= [M(f)]_{ij} \sum_b [M(f)]_{ba} w_b \\ &= \sum_b [M(f)]_{ba} [M(f)]^{tr, -1}_{ij} e_{bj}(v_j) \\ &= \sum_b [M(f)]_{ba} [M(f)]^{tr, -1}_{ji} e_{bj}(v_j) \\ \Rightarrow \tilde{T}(f) e_{ai} &= \sum_b [M(f)]_{ba} [M(f)]^{tr, -1}_{ki} e_{bk} \end{aligned}$$

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$$\langle v, w \rangle = \frac{1}{|G|} \sum_g \langle T(g)v, T(g)w \rangle$$

This is the unitarization discussed in the lecture.  $\langle v, w \rangle_2 = \int df \langle T(f)v, T(f)w \rangle$