

P 7. Quaternions  $\rightarrow V$ .

There are many homomorphisms.

One example:

$$Q = \{ \pm 1, \pm i, \pm j, \pm k \} \quad V = \{ 1, a, b, ab \}$$

$$\varphi: Q \rightarrow V$$

$$\text{define } \varphi(i) = a, \quad \varphi(j) = b, \quad \varphi(1) = \varphi(i^2) = \varphi(i)\varphi(i) = ab$$

$$\varphi(-1) = \varphi(i)\varphi(i) = a^2 = 1$$

$$\varphi(-i) = \varphi(i)\varphi(-1) = a$$

$$\varphi(-j) = b, \quad \varphi(-k) = ab$$

$$\ker \varphi = \{ \pm 1 \} \cong \mathbb{Z}_2$$

$$\text{im } \varphi = V$$

P 8.

$$\begin{array}{ccc} \mathbb{Z}_N & \xrightarrow{m_{k_1}} & \mathbb{Z}_N \\ \downarrow \varphi & & \downarrow \varphi \\ \mu_N & \xrightarrow{P_{k_2}} & \mu_N \end{array}$$

commutes  $\iff k_1 = k_2 \pmod N$

①  $\Leftarrow$  trivial.

②  $\Rightarrow$  if  $k_1 \neq k_2 \pmod N$

$$\hookrightarrow: P_{k_2}(\varphi(\bar{i})) = P_{k_2}(\omega^{i+N}) = \omega^{ik_2 \pmod N}$$

$$\searrow: \varphi(m_{k_1}(\bar{i})) = \varphi(\overline{k_1 i}) = \omega^{ik_1 \pmod N}$$

$$\forall i, ik_1 = ik_2 \pmod N$$

$$k_1 = k_2 \pmod N.$$

P 9.  $T: \mathbb{C}^2 \rightarrow \mathbb{C}^2$  equivariant  $\Rightarrow T(\vec{z}) = \alpha \vec{z}, \alpha \in \mathbb{C}$ .

$$\begin{array}{ccc} \mathbb{C}^2 & \xrightarrow{T} & \mathbb{C}^2 \\ \text{surj} \downarrow & & \downarrow \text{surj} \\ \mathbb{C}^2 & \longrightarrow & \mathbb{C}^2 \end{array}$$

$$\mu \cdot T(\vec{z}) = T(\mu \cdot \vec{z}), \forall \vec{z} \in \mathbb{C}^2, \forall \mu \in \text{Surj} \Rightarrow [T, \mu] = 0$$

$$T = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \mu_1 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \quad \mu_2 = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}$$

$$T\mu_1 = \mu_1 T \Rightarrow \begin{pmatrix} b & -a \\ d & -c \end{pmatrix} = \begin{pmatrix} -c & -d \\ a & b \end{pmatrix} \Rightarrow T = \begin{pmatrix} a & b \\ -b & a \end{pmatrix}$$

$$T\mu_2 = \mu_2 T \Rightarrow \begin{pmatrix} bi & ai \\ ai & -bi \end{pmatrix} = \begin{pmatrix} -bi & ai \\ ai & bi \end{pmatrix} \Leftrightarrow b=0 \Rightarrow T = a \cdot \mathbb{1}_2$$

$$\Rightarrow T(\vec{z}) = \alpha \vec{z}, \alpha \in \mathbb{C}$$

P 10.  $D_3 \cong S_3$

$$D = \langle a, b \mid a^2 = b^3 = (ab)^2 = 1 \rangle$$

$$\varphi: D_3 \rightarrow S_3$$

$$\varphi(a) = (12)$$

$$\varphi(b) = (123)$$

$$P 11. (1) d = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ n & n-1 & n-2 & \dots & 1 \end{pmatrix}$$

$$= \begin{cases} (1\ n)(2\ n-1) \dots \left(\frac{n-1}{2} \ \frac{n+3}{2}\right) & n \text{ odd} \\ (1\ n)(2\ n-1) \dots \left(\frac{n}{2} \ \frac{n}{2}+1\right) & n \text{ even} \end{cases}$$

$$= \prod_{i=1}^{\lceil \frac{n-1}{2} \rceil} (i, n+1-i)$$

$$(2) \lceil \frac{n-1}{2} \rceil \text{ even} \Leftrightarrow n = 4k, 4k+1 \quad (k \in \mathbb{N})$$

$$\text{odd} \Leftrightarrow n = 4k+2, 4k+3$$

(3) recall from lecture that

$$\begin{aligned} (ij) &= (i, i+1)(i+1, j)(i, i+1) \quad (i < j-1) \\ &= \sigma_i (i+1, j) \sigma_i \\ &= \sigma_i \sigma_{i+1} (i+2, j) \sigma_{i+1} \sigma_i \end{aligned}$$

alternatively,

$$\phi = (n-1, n)(n-2, \dots, n) \dots (1\ 2\ 3\ 4 \dots n)$$

$$\text{and } (i, i+1, \dots, j+1) = \sigma_i \sigma_{i+1} \dots \sigma_j$$