

$$\left. \begin{aligned} [(QP)\psi](\omega^k) &= [Q \cdot (P\psi)](\omega^k) = \omega^k (P\psi)(\omega^k) \\ &= \omega^k \psi(\omega^{k-1}) \\ [P(Q\psi)](\omega^k) \end{aligned} \right\}$$

$$\phi: G \times X \rightarrow X$$

$$(\delta, x) \mapsto \delta \cdot x$$

\Rightarrow Induced action on the vector space of functions on X : $\mathcal{F}[X \rightarrow K]$

$$\left. \begin{aligned} f_1, f_2 \in \mathcal{F} \quad f_1(x) = a \in K \quad f_2(x) = b \in K \\ (f_1 + f_2)(x) &= f_1(x) + f_2(x) \\ c \cdot f &\in \mathcal{F} \end{aligned} \right\}$$

$$\tilde{\phi}(\delta, f)(x) = f(\phi(\delta^{-1}, x))$$

$$(\delta \cdot f)(x) = f(\delta^{-1}x)$$

$$\underline{\delta_1 \cdot \delta_2 \cdot f}(x) = \delta_2 \cdot f(\delta_1^{-1}x) = f(\delta_2^{-1} \delta_1^{-1}x) = (\delta_1 \delta_2) \cdot f(x)$$

Application: stabilizer code.

$$P^n = (P')^{\otimes n} \quad P' = \{ \pm I, \pm i, \pm X, \pm Y, \dots \}$$

$$\begin{aligned} X|0\rangle &= |1\rangle & Z|0\rangle &= |0\rangle \\ X|1\rangle &= |0\rangle & Z|1\rangle &= -|1\rangle \end{aligned}$$

Select a subgroup $S \subset P^n$

$$V_S = \{ |\psi\rangle : S|\psi\rangle = |\psi\rangle, \forall S \in S \} \subset \mathcal{H}^n$$

Quantum error

①

0	$\xrightarrow{1-p}$ \swarrow^p \searrow_p $\xrightarrow{1-p}$	0
1	$\xrightarrow{1-p}$ \swarrow^p \searrow_p $\xrightarrow{1-p}$	1

(P << 1)

$\alpha|0\rangle + \beta|1\rangle \xrightarrow{\text{noise}} \alpha|1\rangle + \beta|0\rangle$

②

$ 0\rangle \rightarrow 000\rangle$	$\alpha 001\rangle + \beta 110\rangle$ <hr style="width: 100%;"/> $\downarrow X_3$ $\alpha 000\rangle + \beta 111\rangle$?
$ 1\rangle \rightarrow 111\rangle$		$\alpha 000\rangle + \beta 111\rangle$

Stabilizer formalism (3-qubit)

S = { I, Z₁Z₂, Z₂Z₃, Z₁Z₃ } = < Z₁Z₂, Z₂Z₃ > ≅ Z₂ × Z₂

$$\begin{aligned} Z|0\rangle &= |0\rangle \\ Z|1\rangle &= -|1\rangle \end{aligned}$$

(2)

$$z_1 z_2: \underline{1000}, 1001, 1110, \underline{1111}$$

$$z_2 z_3: \underline{1000}, 1100, 1011, \underline{1111}$$

$$U_3 = \text{span} \{ \underline{1000}, \underline{1111} \}$$

$$\text{Error set: } \langle x_1, x_2, x_3 \rangle$$

$$\{ x_i \cdot z_i \} = 0$$

If E anticommutes with $s \in S$

$$s|\varphi\rangle = -|\varphi\rangle$$

$$\underline{sE|\varphi\rangle} = -E s|\varphi\rangle = -|\varphi\rangle \quad E|\varphi\rangle \in \underline{U_s^\perp}$$

\Rightarrow detectable

If E commutes $\forall s \in S$ ($E \in N(S) \sim S$)

$$N(S) = \{ f \in \mathbb{P}^n, f^s = s f, \forall s \in S \}$$

$$\underline{sE|\varphi\rangle} = E s|\varphi\rangle = \underline{E|\varphi\rangle} \quad E|\varphi\rangle \in \underline{U_s}$$

\Rightarrow undetectable

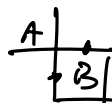
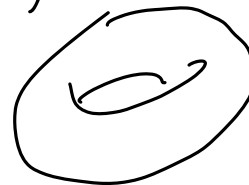
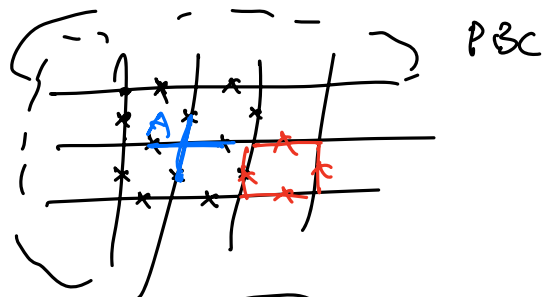
Toric code (Kitaev, Ann. Phys. 2006)

$$A_v = \prod_{j \in \text{star } v} Z_j$$

$$B_p = \prod_{j \in \text{plaq.}} X_j$$

$$H = - \sum_v A_v - \sum_p B_p$$

$$\underline{[A_v, B_p] = 0}$$



$S = \langle \{A_v\}, \{B_p\} \rangle$ stabilize the code space \mathcal{V}_S

N u.c. 2^{2N}

$$A|\varphi\rangle = |\varphi\rangle$$

$$A_v^2 = B_p^2 = 1$$

$$B_p|\varphi\rangle = |\varphi\rangle$$

every A/B cuts the space in half

$2N$ operators, + $\prod A = \prod B = 1$

(only $N-1$ A/B independent)

$\Rightarrow 2(N-1)$ constraints

$$\underline{2^{2N - (2N-2)} = 2^2 = 4}$$

l -bit, k -independent generators of S

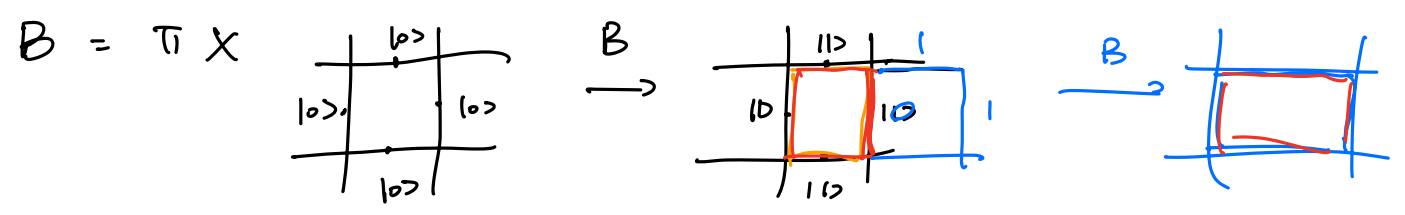
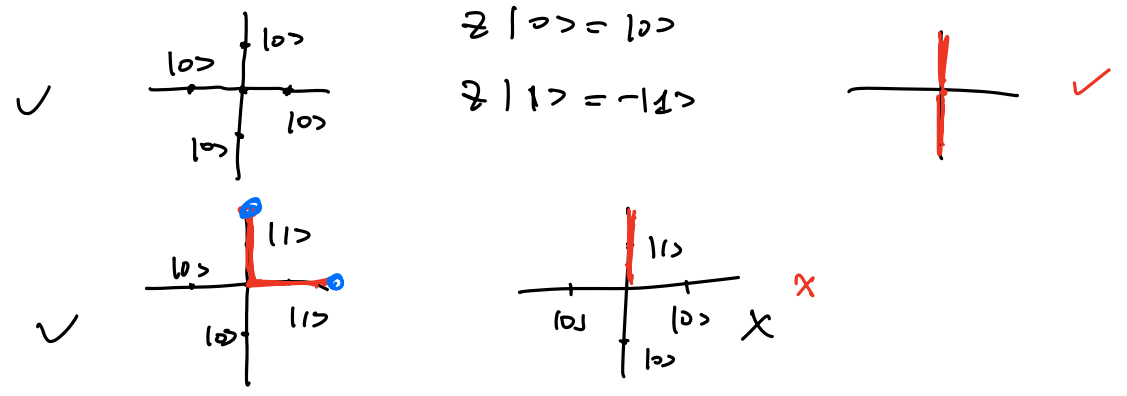
$$\dim(S) = 2^{l-k}$$

$$l = 2N$$

$$k = 2N-2$$

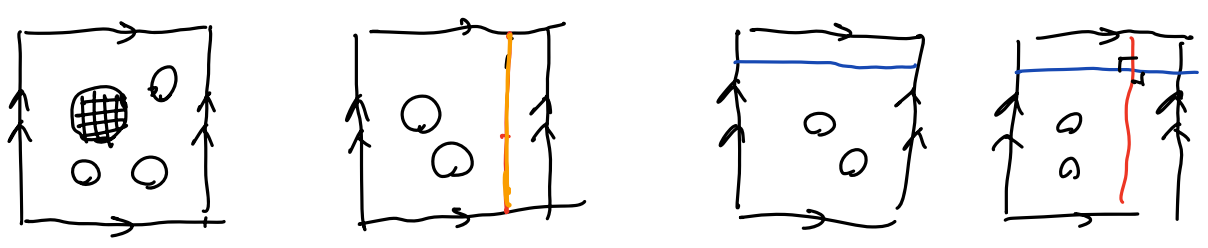
\Rightarrow Toric code encodes two qubits.

A:

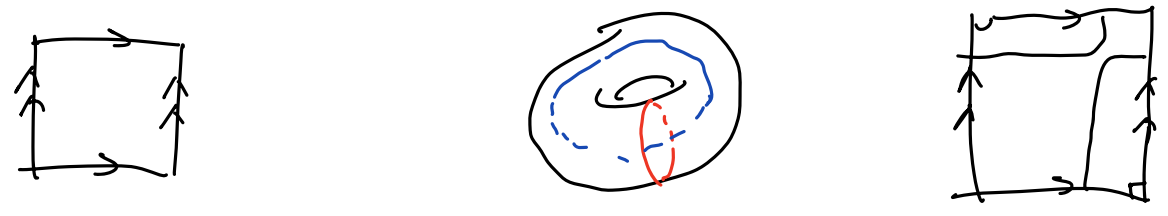


\Rightarrow GS = ^{equal weight} superposition of all closed loops

typical config.



$\mathbb{Z}_2 \times \mathbb{Z}_2$ $(0, 0)$ $(1, 0)$ $(0, 1)$ $(1, 1)$
 \downarrow $|00\rangle$ $|10\rangle$ $|01\rangle$ $|11\rangle$



local noise/error $\pi Z, \pi X$ suppressed.

Bit operations via string operators across the lattice

$$\pi X \left\{ \begin{array}{c} \text{[Square with vertical red dashed line and 'x' marks]} \\ |b\rangle \end{array} \right\} = \left\{ \begin{array}{c} \text{[Square]} \\ |0\rangle \end{array} \right\}$$

$$GS = \frac{1}{\mathcal{N}} \left(\begin{array}{c} \text{[Square]} \\ \text{[Square with } B_p \text{]} \\ \text{[Square with } B_f \text{]} \end{array} + \begin{array}{c} \text{[Square with } B_p \text{]} \\ \text{[Square with } B_f \text{]} \end{array} + \dots \right)$$

Review of Group part

1. Definition of groups $(G, e, \underline{m}, \underline{I})$

① set G .

② $e \in G \quad e f = f \cdot e = f$.

③ $m: G \times G \rightarrow G$

④ $I: G \rightarrow G$

$G = \mathbb{Z} \cdot \mathbb{R} \cdot \mathbb{C}$ groups if $m = "+"$

not if $m = "x"$

$\mathbb{R}^* = (\mathbb{R} - \{0\}), \quad \mathbb{C}^* = (\mathbb{C} - \{0\})$

$\hookrightarrow |G|$ order $\begin{cases} \text{finite} \\ \text{infinite} \end{cases}$ group

$\hookrightarrow g_1 g_2 = g_2 g_1 \quad \forall g_1, g_2 \rightarrow$ abelian

$\Delta \rightarrow$ noabelian.

2. Direct product $H \times G$.

$$(h_1, g_1) \cdot (h_2, g_2) = (h_1 \cdot h_2, g_1 \cdot g_2)$$

↳ semidirect product $H \rtimes G$. $h \in H$. $g \in G$. ⑦

$$\underline{(h_1, g_1)} \cdot \underline{(h_2, g_2)} = \underline{(h_1 \alpha_{g_1}(h_2), g_1 g_2)}$$

$$\begin{aligned} \{ R_1 | \vec{r} \} \{ R_2 | \vec{r}_2 \} &= \{ R_1 | \tau_1 \} (R_2 \vec{r} + \vec{c}_2) \\ &= R_1 R_2 \vec{r} + R_1 \vec{c}_2 + \vec{c}_1 \end{aligned}$$

$$(\tau_1, R_1)(\tau_2, R_2) = (R_1 \vec{c}_2 + \vec{c}_1, R_1 R_2)$$

↳ symplectic space groups

3. subgroups $H \subset G$.

$$\underline{\mu}: H \times H \rightarrow H$$

$$\underline{\Gamma}: H \rightarrow H$$

G has trivial subgroups $\{e\}$ and G .

proper subgroup $H \neq G$

$$\mathbb{Z} \subset \mathbb{R} \subset \mathbb{C} \quad \text{"+"}$$

$$\hookrightarrow H \triangleleft G: gHg^{-1} = H \quad (\forall g \in G)$$

↳ simple group, no nontrivial normal subgroup.

$$\hookrightarrow \text{centralizer } C_G(h) = \{ g \in G: gh = hg \} \subset G$$

$$C_G(H) = \{ g \in G: gh = hg, \forall h \in H \} \subset G$$

$$\text{normalizer } N_G(H) = \{ g \in G: gHg^{-1} = H \}$$

$$C_G(H) \subset N_G(H)$$

4. $GL(n, K)$

$$\hookrightarrow SL(n, K)$$

$$\left. \begin{array}{l} O(n, K), SO(n, K) \\ U(n, K), SU(n, K) \end{array} \right\} \underline{\det}$$

$$A^T \underline{J} A = \underline{J} \left\{ \begin{array}{l} J_{p,q} = \begin{pmatrix} -1 & p \\ & q \end{pmatrix} \\ \text{symplectic } J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \end{array} \right.$$

Homomorphism / isomorphism.

5. Homomorphism. $\varphi: G \rightarrow G'$

$$\begin{array}{ccc} G \times G & \xrightarrow{m} & G \\ \varphi \times \varphi \downarrow & & \downarrow \varphi \\ G' \times G' & \longrightarrow & G' \end{array}$$

$$\varphi(g_1) \cdot_{G'} \varphi(g_2) = \varphi(g_1 \cdot_G g_2)$$

$$\left\{ \begin{array}{l} \varphi(e) = e' \\ \varphi(g^{-1}) = \varphi(g)^{-1} \end{array} \right.$$

$$\ker / \text{im} : \quad \ker \varphi = \{ g \in G : \varphi(g) = 1_{G'} \}$$

$$\text{im } \varphi = \varphi(G)$$

① $\pi: SU(2) \rightarrow SO(3)$

$$u \vec{x} \cdot \vec{r} \cdot u^+ := (\pi(u) \cdot \vec{x}) \cdot \vec{r}$$

$$\ker \pi = \{\pm 1\} \cong \mathbb{Z}_2$$

② $\Gamma: G \rightarrow \underline{GL(V)}$ V some $\sqrt[n\text{-dim}]{} \text{vector space over } k$
given basis

$$GL(V) \cong \underline{GL(n, k)}$$

isomorphism: homo. + (1-1 & onto)

1-1: $\ker \varphi = \{e\}$

onto: $\varphi(G) = G'$

$$\varphi: G \rightarrow G' : \text{Aut}(G)$$

isomorphism defines an equivalence relation

$$M \cong N \cong \mathbb{Z}_n$$

matrix-rep. $T: G \rightarrow GL(n, k)$

$$T(g) \hat{e}_i = T(g)_{ij} \hat{e}_j$$

↳ equivalent rep $T \cong T'$, $\exists S$ s.t.

$$T'(g) = S T(g) S^{-1} \quad \forall g \in G.$$

more generally conj. rep $\varphi_{1,2}: G \rightarrow G'$

$$\varphi_2(g) = g_2 \varphi_1(g) g_2^{-1}$$

6. define group action by homomorphism.

$$\alpha : G \rightarrow S_X := \{ \sigma : X \rightarrow X \}$$

Set of permutations

$$g \mapsto \phi(g, \cdot)$$

$$\alpha_g(x) = \phi(g, x) = g \cdot x$$

$$g_1(g_2 \cdot x) = (g_1 g_2) \cdot x$$

↳ orbits. $Orb_G(x) = \{ g \cdot x \mid g \in G \}$

① defines equivalence relation

$$x \sim y \iff y = g \cdot x$$

② orbits partition G .

$$O_G(x) = O_G(x') \text{ or}$$

$$O_G(x) \cap O_G(x') = \emptyset.$$

X/G set of orbits

↳ fixed points

$$Fix_X(G) = \{ x \in X : g \cdot x = x \} \subset X$$

↳ stabilizer.

$$Stab_G(x) := \{ g \in G : g \cdot x = x \} \subset G.$$

(G^x)

a group action is

$$1. \text{ effective : } \text{Fix}_x(g) \neq X \quad \forall g \neq e$$

$$2. \text{ transitive : } \text{Orb}_G(x) = X \quad \forall x \in X$$

$$3. \text{ free. : } \text{Fix}_x(g) = \emptyset \quad \forall g \neq e$$

Theorem (Stabilizer - orbit)

$$\begin{aligned} \text{Orb}_G(x) &\xrightarrow{\cong} G/G^x \\ g \cdot x &\mapsto gG^x \end{aligned}$$

$$|\text{Orb}_G(x)| = [G : G^x]$$