

# Recap Groups. subgroups

$$1 \quad (G, m, I, e)$$

$\uparrow \quad \uparrow \quad \uparrow$   
set

$$g_1 (g_2 g_3) = (g_1 g_2) g_3$$

$$\underline{m} \cdot \underline{I}$$

$$m: G \times G \rightarrow G$$

$$I: G \rightarrow G$$

uniqueness  $e$ ,  $\forall a \rightarrow a^{-1}$

2. subgroup.  $H \subset G$ .  $\underline{m} \cdot \underline{I}$

3. order  $|G|$

4. direct product:  $\mathbb{Z}_2 \times \mathbb{Z}_2 \rightarrow V$

5.  $GL(n, K)$

$$O(n, K)$$

$$AA^T = \mathbb{1} \quad (= A^T A = \mathbb{1})$$

$$SO(n, K)$$

$$\det A = 1$$

$$U(n) \subset GL(n, \mathbb{C})$$

$$AA^\dagger = \mathbb{1}$$

$$SU(n)$$

$$\det = 1$$

①

$$A J A^T = J_{p, q} \rightarrow \mathcal{O}(1, 3)$$

$$\left| \det A = 1 \quad A \in Sp(2n) \right|^{Sp(2n)}$$


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Example (HW)  $Sp(2n, k)$  & canonical transformations

$q^i, p_i$  ( $i=1, \dots, n$ ) coordinates & momentum.

$$f(q, \vec{p}), \quad g(\vec{q}, \vec{p}).$$

Poisson bracket

$$\{f, g\} = \sum_{i=1}^n \left( \frac{\partial f}{\partial q^i} \frac{\partial g}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial q^i} \right)$$

$$\Rightarrow \{q^i, q^j\} = \{p_i, p_j\} = 0$$

$$\{q^i, p_j\} = \delta^i_j$$

Canonical transform  $\rightarrow \vec{Q}, \vec{P}$

$$\begin{pmatrix} Q^1 \\ Q^2 \\ \vdots \\ P^1 \\ P^2 \\ \vdots \\ P^1 \\ P^2 \\ \vdots \end{pmatrix} = A \begin{pmatrix} q^1 \\ q^2 \\ \vdots \\ p^1 \\ p^2 \\ \vdots \end{pmatrix}$$

$$\{Q^i, Q^j\} = \{P_i, P_j\} = 0 \quad \{Q^i, P_j\} = \delta^i_j$$

$$\Leftrightarrow \underline{\underline{A \in Sp(2n)}}$$

Definition: if  $X$  is a subset of  $G$ . then the ②  
 smallest subgroup of  $G$  containing  $X$ ,  
 denoted  $\langle X \rangle$ , is called the subgroup  
generated by  $X$ . or we say  $X$  generates  $\langle X \rangle$

Remarks.

1.  $G = \langle X \rangle$ .  $X$  generates  $G$ .

$|X| < \infty$ . "finitely generated"

2. group presentation:

$$G = \langle g_1, \dots, g_n \mid R_1, \dots, R_r \rangle$$

↑  
generating elements

↗ relation

3.  $1/e$  is usually not included.

Example:

$$\mathbb{Z}_n \text{ or } \mu_n: \langle A \mid A^n = 1 \rangle$$

$$\mu_n: \langle \omega = e^{i\frac{2\pi}{n}} \mid \omega^n = 1 \rangle$$

$$\mathbb{Z}_n: \langle \bar{1} \mid (\bar{1})^n = \bar{0} \rangle$$

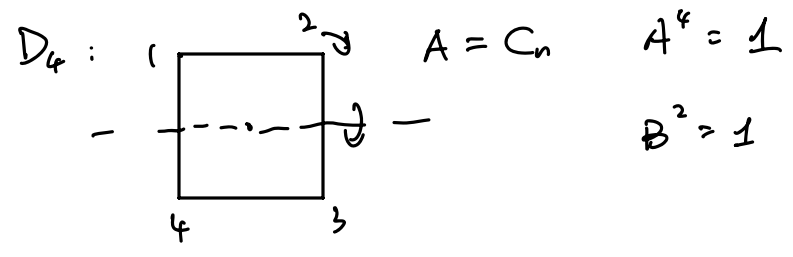
$$\underbrace{\bar{1} + \bar{1} + \dots + \bar{1}}_n$$

$$4\text{-group: } \mathbb{Z}_2 \times \mathbb{Z}_2: \langle A, B \mid A^2 = B^2 = (AB)^2 = 1 \rangle$$

$$A^m B^n: \underline{1, A, B, AB} \quad A^2 B = B$$

$$\text{dihedral } D_n: \langle A, B \mid A^n = B^2 = (AB)^2 = 1 \rangle$$

$$D_2 \cong \mathbb{Z}_2 \times \mathbb{Z}_2$$



Example. Quaternion group.

$$i^2 = j^2 = k^2 = -1 \quad ij = -ji = k$$

$$\begin{cases} jk = -kj = i \\ ki = -ik = j \end{cases}$$

$$Q = \{ \pm 1, \pm i, \pm j, \pm k \}$$

$$= \langle x, y \mid x^4 = 1, x^2 = y^2, y^{-1}xy = x^{-1} \rangle$$

$$= \langle ij \rangle \curvearrowright$$

Pauli matrices:  $\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$$\sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\sigma^i \sigma^j = \delta^{ij} + i \epsilon^{ijk} \sigma^k \quad ( [\sigma^i, \sigma^j] = 2i \epsilon^{ijk} \sigma^k )$$

$$\Rightarrow i = -i\sigma^1, \quad j = -i\sigma^2, \quad k = -i\sigma^3$$

$$Q = \langle -i\sigma^1, -i\sigma^2 \rangle \subset SU(2)$$

Example Pauli group.

$$P_1 = \{ \pm 1, \pm i, \pm \sigma^1, \pm \sigma^2, \pm \sigma^3, \pm i\sigma^1, \pm i\sigma^2, \pm i\sigma^3 \}$$

$$= \langle \sigma^1, \sigma^2, \sigma^3 \rangle \quad \bar{i} = \sigma^1 \sigma^2 \sigma^3$$

X Y Z

Qubit two-dim. Hilbert space

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad |\varphi\rangle = \alpha|0\rangle + \beta|1\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

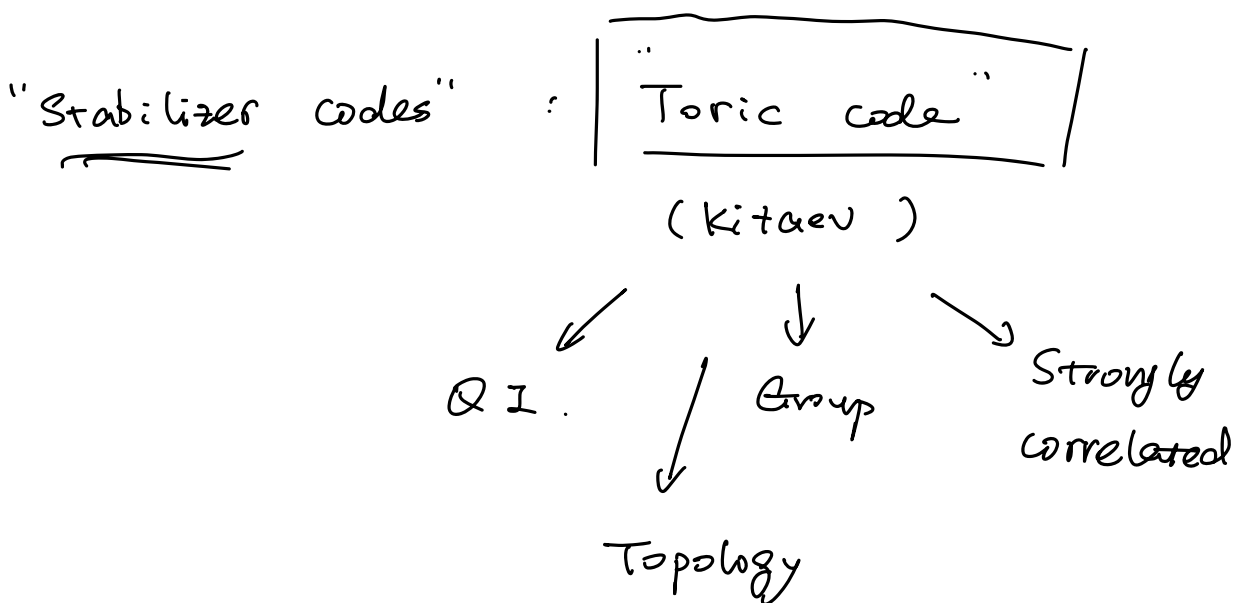
$$X|0\rangle = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = |1\rangle$$

$$X|1\rangle = |0\rangle$$

$$Z|0\rangle = |0\rangle$$

$$Z|1\rangle = -|1\rangle$$

X : "bit-flip"  
NOT  
"phase-flip"



### 3. Homomorphism & Isomorphism

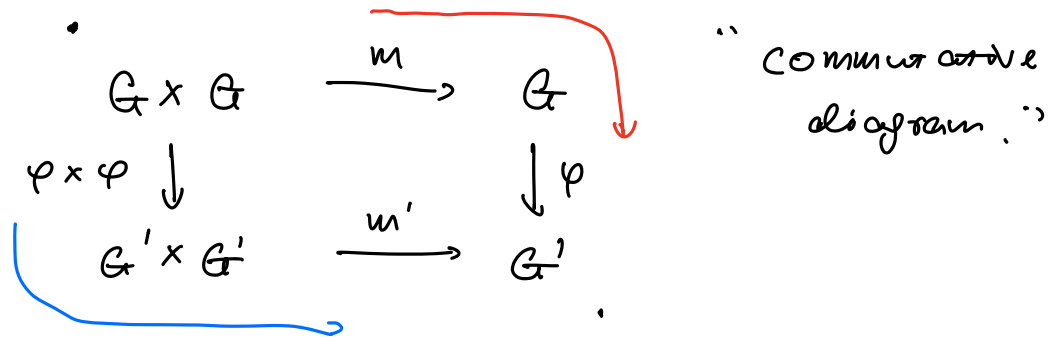
Definition . Let  $(G, m, I, e)$  &  $(G', m', I', e')$

be two groups.

Homomorphism  $\varphi : G \rightarrow G'$ , s.t.  $\forall g_1, g_2 \in G$

$$\varphi(\underline{m(g_1, g_2)}) = \underline{m'(\varphi(g_1), \varphi(g_2))}$$

$$(\varphi(g_1, g_2) = \varphi(g_1) \cdot \varphi(g_2))$$

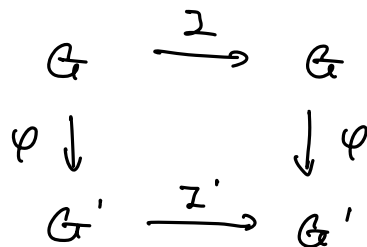


$$\varphi(e) = \varphi(e \cdot e) = \varphi(e) \varphi(e)$$

$$a' = a' \cdot a'$$

$$a' = a' \cdot (a')^{-1} = e'$$

inversion:



$$\varphi(e) = \varphi(g \cdot g^{-1})$$

$$= \underline{\varphi(g)} \cdot \underline{\varphi(g^{-1})}$$

$$= e'$$

$$\Rightarrow \underline{\varphi(g^{-1})} = \underline{(\varphi(g))^{-1}}$$

Remarks :

1.  $\varphi(g) = e'$  . iff  $g = e$   $\varphi$  is injective

$$\parallel \quad \forall g_1, g_2 \in G.$$

$$\parallel \quad \varphi(g_1) = \varphi(g_2) \Rightarrow g_1 = g_2$$

$$e' = \varphi(g_1) \cdot \varphi(g_2)^{-1} = \varphi(\underline{g_1 g_2^{-1}}) = \varphi(\underline{g_3 = e})$$

2.  $\forall g' \in G'$  .  $\exists g \in G$  . s.t.  $\varphi(g) = g'$  surjective

3. (Def)  $\varphi$  is an isomorphism if both injec.  
& surjec.  
(bijective)

$$G \begin{array}{c} \xrightarrow{\varphi} \\ \xleftarrow{\varphi^{-1}} \end{array} G'$$

$\varphi^{-1}$  is also an isomorphism.

(HW)

isomorphism defines an equivalence relation.

"isomorphic groups are the same".

4. (Def)  $G' = G$   $\varphi: G \rightarrow G$

isomorphism  $\Rightarrow$  "automorphism"

## Definition (kernel & image)

$$\varphi \text{ homo.} \quad \varphi: G \longrightarrow H$$

(a) kernel  $K$

$$K = \ker \varphi := \{ g \in G : \varphi(g) = 1_H \}$$

(b) image

$$\begin{aligned} \text{im } \varphi &:= \{ h \in H : \exists g \in G. \text{ s.t. } \varphi(g) = h \} \\ &= \varphi(G) \end{aligned}$$

## Remarks

(a)  $\varphi(G) \subset H$  is a subgroup.

$$\textcircled{1} \varphi(1_G) = 1_H$$

$$\textcircled{2} \forall h_1 = \varphi(g_1), h_2 = \varphi(g_2)$$

$$h_1 h_2 = \varphi(g_1) \varphi(g_2) = \varphi(g_1 g_2) \in \varphi(G)$$

$$\textcircled{3} h_1 = \varphi(g_1) \quad 1_H = \varphi(g_1 \cdot g_1^{-1}) = \underbrace{\varphi(g_1)}_{h_1} \cdot \underbrace{\varphi(g_1^{-1})}_{\underline{h_2^{-1}}}$$

$$\varphi(G) \ni h_1 = h_1^{-1}$$

(b)  $K = \ker \varphi$  is a subgroup of  $G$ .

(c)  $\varphi$  is an isomorphism.

$$\ker \varphi = \{ 1 \} \quad \text{inj.}$$

$$\text{im } \varphi = H \quad \text{surj.}$$



Example,  $\mu_N$  &  $\mathbb{Z}_N$

$$\mu_N = \{1, \omega, \omega^2, \dots, \omega^{N-1}\}$$

$$\mathbb{Z}_N = \{\bar{0}, \bar{1}, \dots, \overline{N-1}\}$$

$$\varphi: \mathbb{Z}_N \rightarrow \mu_N$$

$$r' \in r + N\mathbb{Z}$$

$$\varphi(\bar{r} = r + N\mathbb{Z}) := e^{i \frac{2\pi}{N} r'}$$

$$\textcircled{1} \varphi(\bar{r}_1 + \bar{r}_2) = \varphi(\bar{r}_1) \varphi(\bar{r}_2) \quad \checkmark$$

$$\textcircled{2} \varphi(\bar{r}) = 1 \Leftrightarrow \bar{r} = \bar{0} \quad \checkmark$$

$$\textcircled{3} \forall \omega^j \in \mu_N, \exists \varphi(\bar{r}_j) = \omega^j \quad \checkmark$$

*$\varphi$  an  
isomorphism*

Example, power map.

$$P_k: \mu_N \rightarrow \mu_N$$

$$P_k(z) = z^k$$

$$\textcircled{1} (z_1, z_2)^k = z_1^k z_2^k \quad \checkmark$$

$$\textcircled{2} \text{isomorphism? } \gcd(k, N) = 1$$

$$k = N\mathbb{Z} \quad P_k(z) = 1 \quad \text{trivial}$$

(9)

$$\mu_4 \rightarrow \mu_4 \quad k=2$$

$$\begin{array}{l}
 1 \rightarrow 1 \\
 i = e^{i\frac{2\pi}{4}} \rightarrow -1 \\
 -1 \rightarrow 1 \\
 -i \rightarrow -1
 \end{array}$$

$$\begin{array}{l}
 \ker(p_2) = \{\pm 1\} \\
 \text{im}(p_2) = \{\pm 1\} \\
 \cong \mathbb{Z}_2
 \end{array}$$

$$m_k: \mathbb{Z}_N \rightarrow \mathbb{Z}_N$$

$$m_k(\bar{r}) = \overline{kr}$$

$$\begin{array}{ccc}
 \mathbb{Z}_N & \xrightarrow{m_k} & \mathbb{Z}_N \\
 \downarrow \varphi & & \downarrow \varphi \\
 \mu_N & \xrightarrow{P_k} & \mu_N \\
 & P_{k_2} &
 \end{array}$$

$$\varphi \circ m_k = P_k \circ \varphi$$

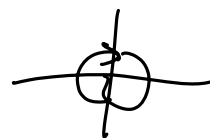
commute iff  $k_1 = k_2 \pmod N$ .

Example

$$\varphi: U(1) \rightarrow SU(2)$$

$$\varphi(z) := \begin{pmatrix} z^N & 0 \\ 0 & z^{-N} \end{pmatrix}$$

$$e^{i\theta} = \tau \in U(1)$$



$$\underline{(e^{i\theta})^N = 1}$$

$$\ker(\varphi) \cong \mu_N$$

Example  $SU(2) \leftrightarrow SO(3) \quad \mathbb{R}^3$

①  $\mathbb{R}^3 \rightarrow 2 \times 2$  ?

Def. homomorphism

$h: \mathbb{R}^3 \rightarrow \mathcal{H}_2^0$  (vector space of  
2x2 traceless matrices)

$$h(\vec{x}) = \vec{x} \cdot \vec{\sigma} = x_i \cdot \sigma^i = \begin{pmatrix} x^3 & x^1 - ix^2 \\ x^1 + ix^2 & -x^3 \end{pmatrix} \in \mathcal{H}_2^0$$

is an isomorphism.

② For a given  $u \in SU(2)$ , define homomorphism  
by conjugation:

$$C_u: \mathcal{H}_2^0 \rightarrow \mathcal{H}_2^0$$

$$C_u(m) := umu^{-1} \quad (m \in \mathcal{H}_2^0)$$

$$\left( \begin{array}{l} \text{tr}(umu^{-1}) = \text{tr}(m) \Rightarrow \\ \text{S} \quad (umu^{-1})^\dagger = \underline{u} m^\dagger u^{-1} = umu^{-1} \\ \Rightarrow C_u(m) \in \mathcal{H}_2^0 \end{array} \right)$$

Define  $R(u) : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  s.t.

$$\begin{array}{ccc}
 \mathbb{R}^3 & \xrightarrow{R(u)} & \mathbb{R}^3 \\
 h \downarrow & & \downarrow h \\
 \mathfrak{H}_2^0 & \xrightarrow{C_u} & \mathfrak{H}_2^0
 \end{array}
 \quad
 \begin{array}{l}
 h \circ R(u) = C_u \circ h \\
 (R(u) \cdot \vec{x}) \cdot \vec{\sigma} = u \vec{x} \cdot \vec{\sigma} u^{-1} \\
 (\vec{x} \in \mathbb{R}^3)
 \end{array}$$

In other words, we define a homomorphism

$$R : \text{SU}(2) \rightarrow \text{GL}(3, \mathbb{R})$$

s.t.  $\forall \vec{x} \in \mathbb{R}^3$ ,  $R(u)$  satisfy

$$u \vec{x} \cdot \vec{\sigma} u^{-1} = (R(u) \vec{x}) \cdot \vec{\sigma}$$

$$\begin{aligned}
 u x_i \sigma^i u^{-1} &= (R(u)_{ji} x_j) \cdot \sigma_j \quad \forall \vec{x} \in \mathbb{R}^3 \\
 \Leftrightarrow u \sigma^i u^{-1} &= R(u)_{ji} \sigma_j
 \end{aligned}$$

$$\begin{aligned}
 (u_1 u_2) \sigma_i (u_1 u_2)^{\dagger} &= u_1 (R(u_2)_{ji} \sigma_j) u_1^{\dagger} \\
 &= R(u_1)_{ji} (u_1 \sigma_j u_1^{\dagger}) \\
 &= \underline{R(u_2)_{ji} R_{kj}(u_1) \sigma_k} \\
 &= R(u_1 u_2)_{ki} \sigma_k \\
 \Rightarrow R(u_1 u_2) &= R(u_1) \cdot R(u_2)
 \end{aligned}$$

$$\textcircled{1} \quad \vec{y} = R(u) \cdot \vec{x} \quad \det(\vec{x} \cdot \vec{\sigma}) = -\vec{y}^2$$

$$\vec{y}^2 = -\det((R(u) \cdot \vec{x}) \cdot \vec{\sigma}) = -\det(u \vec{x} \cdot \vec{\sigma} u^{-1}) = \vec{x}^2$$

$$\Rightarrow R(u) \in O(3)$$

(12)

$$\textcircled{2} \quad R(\mathbb{1}_2 \in \text{SU}(2)) = \mathbb{1}_3 \quad R(u) \stackrel{?}{\in} \text{SO}(3)$$

$$\text{tr}(\sigma^i \sigma^j \sigma^k) = \epsilon_{ijk} \cdot (2i)$$

$$2i = \text{tr}(\underbrace{\sigma^1}_{uu^+} \underbrace{\sigma^2}_{uu^+} \underbrace{\sigma^3}_{uu^+}) = \text{tr}(\underbrace{u\sigma^1 u^+}_{uu^+} \underbrace{u\sigma^2 u^+}_{uu^+} \underbrace{u\sigma^3 u^+}_{uu^+})$$

$$= R_{i1}(u) R_{j2}(u) R_{k3}(u) \text{tr}(\sigma^i \sigma^j \sigma^k)$$

$$= (2i) \cdot \underbrace{\epsilon_{ijk} R_{i1}(u) R_{j2}(u) R_{k3}(u)}$$

$$= (2i) [\det R(u)]$$

$$\Rightarrow \det R(u) = 1$$

$$\Rightarrow R(u) \in \text{SO}(3)$$

$$R(u) = R(-u)$$

$\text{SU}(2)$  double cover  
of  $\text{SO}(3)$

$$\underline{\text{Ker } R} = \{\pm 1\} \cong \mathbb{Z}_2$$